

# Continuum Physics

## Problem set 2

### Problem 1.

Consider a scalar field,  $\phi$ , vector fields  $\mathbf{u}, \mathbf{v}, \mathbf{a}, \mathbf{b}, \mathbf{c}$  and  $\mathbf{d}$ , and a tensor field  $\mathbf{A}$ . Use indicial notation to show the following:

- (i)  $(\mathbf{a} \otimes \mathbf{b})(\mathbf{c} \otimes \mathbf{d}) = (\mathbf{b} \cdot \mathbf{c})\mathbf{a} \otimes \mathbf{d}$
- (ii)  $\nabla \times (\nabla \phi) = \mathbf{0}$
- (iii)  $\nabla \times (\nabla \times \mathbf{v}) = \nabla(\nabla \cdot \mathbf{v}) - \nabla^2 \mathbf{v}$ , where  $\nabla^2 \mathbf{v} := \nabla \cdot \nabla \mathbf{v}$
- (iv)  $\nabla \cdot (\nabla \times \mathbf{v}) = 0$
- (v)  $\nabla(\phi \mathbf{v}) = \phi \nabla \mathbf{v} + \mathbf{v} \otimes \nabla \phi$
- (vi)  $\nabla(\mathbf{u} \cdot \mathbf{v}) = (\nabla \mathbf{v})^T \mathbf{u} + (\nabla \mathbf{u})^T \mathbf{v}$
- (vii)  $\text{div}(\phi \mathbf{A}) = \phi \text{div}(\mathbf{A}) + \mathbf{A} \nabla \phi$
- (viii)  $\text{div}(\mathbf{u} \otimes \mathbf{v}) = \mathbf{u} \text{div}(\mathbf{v}) + (\nabla \mathbf{u}) \mathbf{v}$

### Problem 2.

Let  $I_1, I_2, I_3$  be the principal invariants of a tensor  $\mathbf{A}$ :

$$\begin{aligned} I_1 &= \text{trace}(\mathbf{A}) \\ I_2 &= \frac{1}{2} \left[ (\text{trace}(\mathbf{A}))^2 - \text{trace}(\mathbf{A}^2) \right] \\ I_3 &= \det(\mathbf{A}). \end{aligned}$$

Show that these quantities are indeed invariant under an orthogonal transformation of the basis vectors, given by  $\tilde{\mathbf{e}}_i = \mathbf{Q} \mathbf{e}_i$ .

### Problem 3.

New right-handed coordinate axes are chosen with the new origin at  $(4, -1, -2)$  and with  $\bar{\mathbf{e}}_1 = (2\mathbf{e}_1 + 2\mathbf{e}_2 + \mathbf{e}_3)/3$  and  $\bar{\mathbf{e}}_2 = (\mathbf{e}_1 - \mathbf{e}_2)/\sqrt{2}$ .

- (i) Express  $\bar{\mathbf{e}}_3$  in terms of the  $\mathbf{e}_k$ .
- (ii) If  $\mathbf{t} = 10\mathbf{e}_1 + 10\mathbf{e}_2 - 20\mathbf{e}_3$ , express  $\mathbf{t}$  in terms of the new basis.
- (iii) Express the old coordinates  $X_1, X_2, X_3$  in terms of  $\bar{X}_1, \bar{X}_2, \bar{X}_3$ .

### Problem 4.

A force of magnitude  $F$  acts in a direction radially away from the origin at a point  $(a/3, 2b/3, 2c/3)$  on the surface of the ellipsoid  $(X^2/a^2) + (Y^2/b^2) + (Z^2/c^2) = 1$ . Determine the components of the normal to the surface, and hence the component of the force perpendicular to the surface at  $(a/3, 2b/3, 2c/3)$ .

*Hint:* Recall that the normal to a level surface  $\phi(X, Y, Z) = \text{constant}$  is given by

$$\hat{\mathbf{n}} = \frac{\nabla\phi}{\|\nabla\phi\|}.$$

**Problem 5.**

A tensor  $\mathbf{P}$  is a projection if  $\mathbf{P}$  is symmetric and  $\mathbf{P}^2 = \mathbf{P}$ . Show that the following tensors are projections:

- (i)  $\mathbf{1}$
- (ii)  $\mathbf{0}$
- (iii)  $\mathbf{e} \otimes \mathbf{e}$ , where  $\mathbf{e}$  is any unit vector.
- (iv)  $\mathbf{1} - \mathbf{e} \otimes \mathbf{e}$

**Problem 6.**

Let  $\mathbf{Q}$  be an orthogonal tensor, and  $\mathbf{e}_1$  be of unit magnitude and such that  $\mathbf{Q}\mathbf{e}_1 = \mathbf{e}_1$  and  $\|\mathbf{e}_1\| = 1$ . Also let  $\mathbf{n}$  be any vector orthogonal to  $\mathbf{e}_1$  and of unit magnitude:  $\mathbf{n} \cdot \mathbf{e}_1 = 0$ ,  $\|\mathbf{n}\| = 1$ . Let  $\mathbf{m}$  be such that  $\mathbf{m} \cdot \mathbf{e}_1 = 0$ ,  $\|\mathbf{m}\| = 1$ ,  $\mathbf{m} = \mathbf{Q}\mathbf{n}$  and  $\mathbf{m} \cdot \mathbf{n} = \cos\theta$ .

- (i) Sketch (graphically) the action of  $\mathbf{Q}$  on  $\mathbf{e}_1$  and  $\mathbf{n}$ .
- (ii) Show that  $\mathbf{Q}$  can be written as:

$$\mathbf{Q} = \mathbf{1}\cos\theta + (1 - \cos\theta)\mathbf{e}_1 \otimes \mathbf{e}_1 - (\mathbf{e}_2 \otimes \mathbf{e}_3 - \mathbf{e}_3 \otimes \mathbf{e}_2)\sin\theta,$$

where  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$  form an orthonormal triad.

- (iii) Show that

$$(\mathbf{a} \otimes \mathbf{b} - \mathbf{b} \otimes \mathbf{a})\mathbf{h} = -(\mathbf{a} \times \mathbf{b}) \times \mathbf{h}.$$

- (iv) Show that  $\mathbf{Q}$  can also be written as:

$$\mathbf{Q} = \mathbf{1}\cos\theta + (1 - \cos\theta)\mathbf{e}_1 \otimes \mathbf{e}_1 + \sin\theta\mathbf{E},$$

where  $\mathbf{E}$  is the skew-symmetric tensor of which  $\mathbf{e}_1$  is the axial vector.